



10th International Symposium on Data Assimilation
Kobe, Japan
October 21-25, 2024

Machine Learning methodology for generating ensemble members in Data Assimilation of Earth Observations

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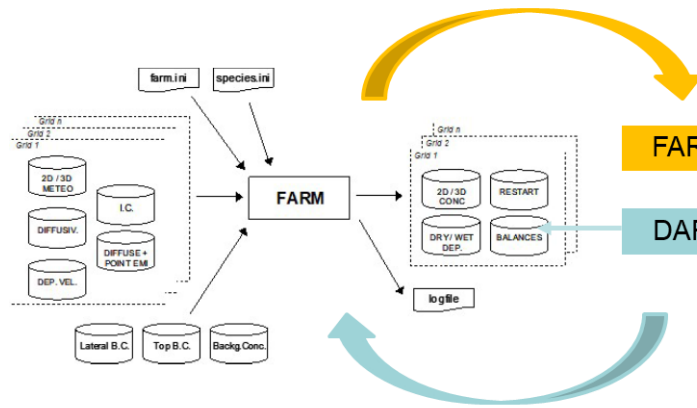


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MILANO 1863



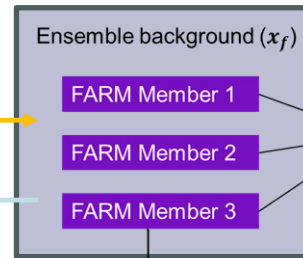
MEEO
Meteorological Environmental
Earth Observation

For each member

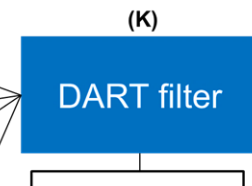


FARM to DART

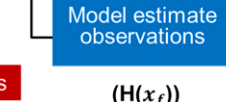
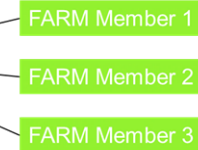
DART to FARM



$$x_a = x_f + K[y^0 - H(x_f)]$$



Ensemble analysis (x_a)



observations

EnAKF with Quantile Conserving Ensemble Filter Framework (QCEFF)

Localize the impacts of the variable only on the model variable state. In other words, NO₂ influences only itself.

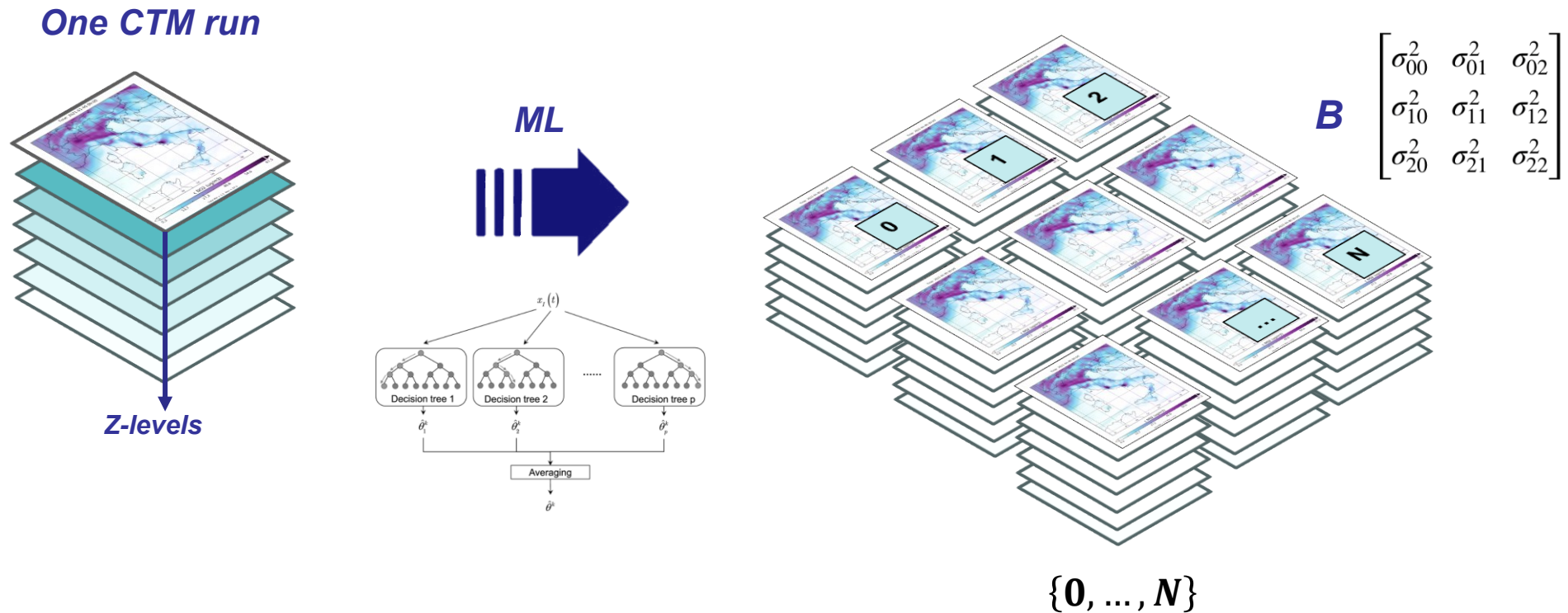
Input.nml
- controls behavior
DART executables



NCAR | DART

Sat Observation in DART format

- I. To generate a stationary ensemble of perturbed, realistic 3D concentration fields that provide a realistic estimate of the model uncertainties, without the need to run the model multiple times
- II. To enable computationally-feasible, operational Data Assimilation (EnOI) of satellite data



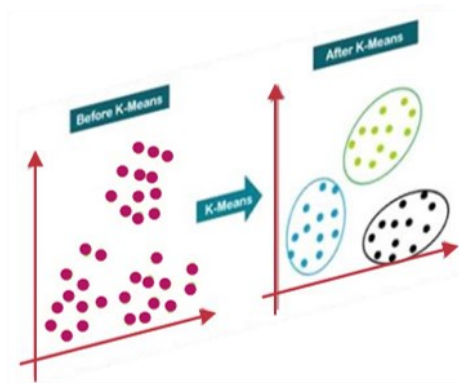
- A constellation of **Low Earth Orbit (LEO) satellites** to advance **environmental monitoring** and management from space
- Equipped with **optical, multispectral, and radar** technologies
- **High spatio-temporal resolution**, focused on the Mediterranean region



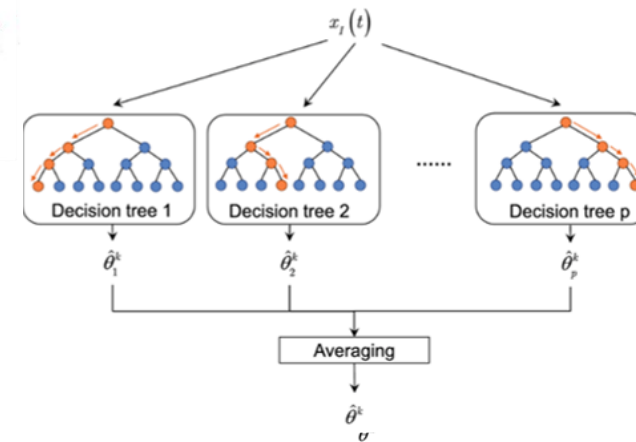
1. Inference Datasets Generation

t_0	$C_{NO_2,(t_0)}$	$C_{i,(t_0)}$	$P_{(t_0)}$	REL	$T_{(t_0)}$	$Sp_{(t_0)}$	$C_{NO_2,(t_0-1)}$	$C_{NO_2,(t_0-2)}$...	$C_{NO_2,(t_0-N)}$...	$T_{(t_0-N)}$
2021-01-01 00:00:00												
2021-01-01 01:00:00												
...												
202x-xx-xx xx:xx:xx												

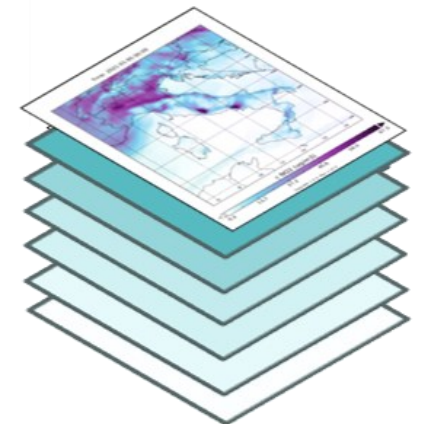
2. Dimensionality reduction



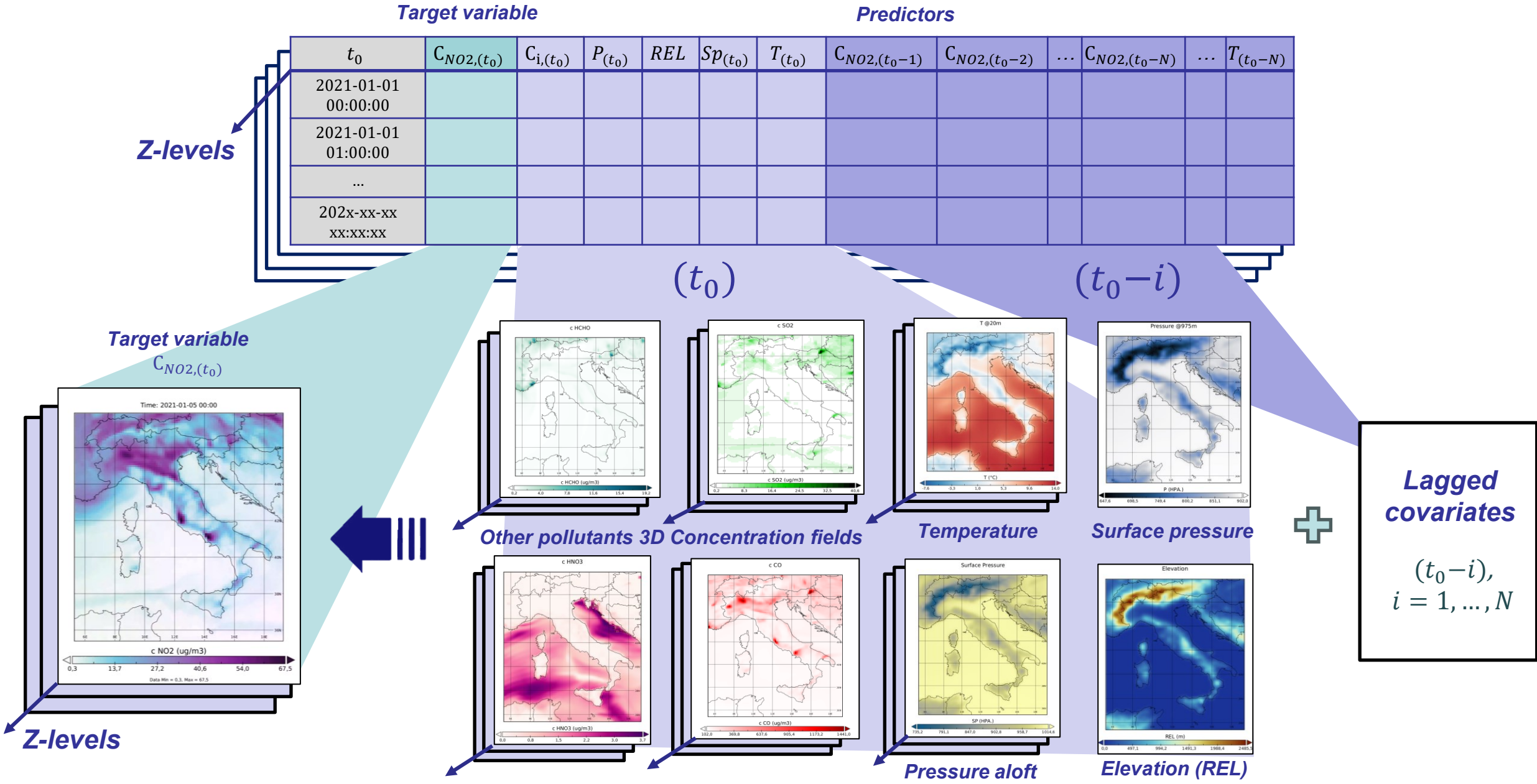
3. Models Training



4. Prediction and 3D field assembly



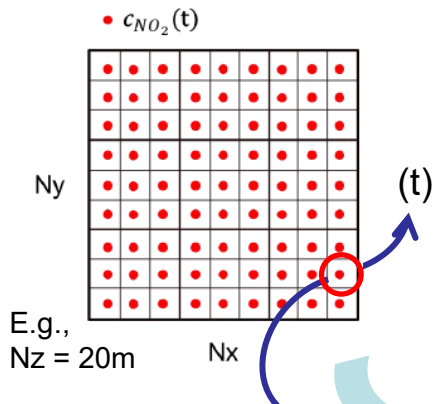
Step 1 : Inference Dataset Generation



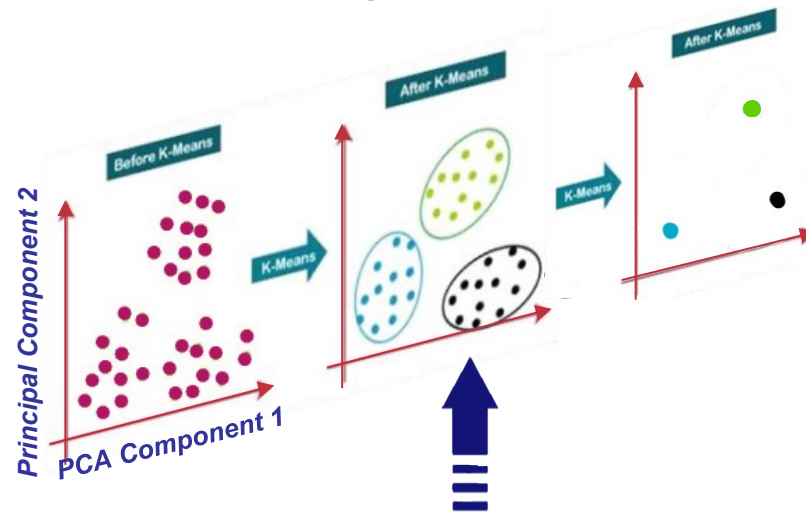
Step 2: PCA/K-Means Clustering

→ Training features reduced from $O(10^7)$ to $O(10^5)$

Time series with similar characteristics are grouped together

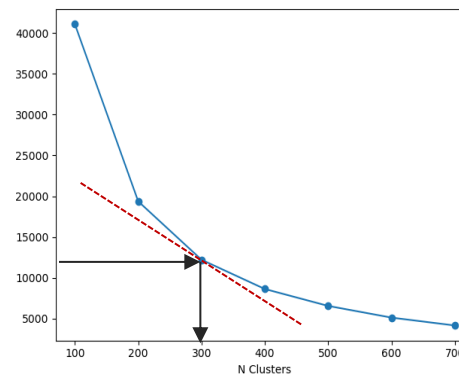


PCA



Mean cluster values are extracted as representatives of the entire cluster

Elbow method to define optimal number of clusters



Step 3: Models Training

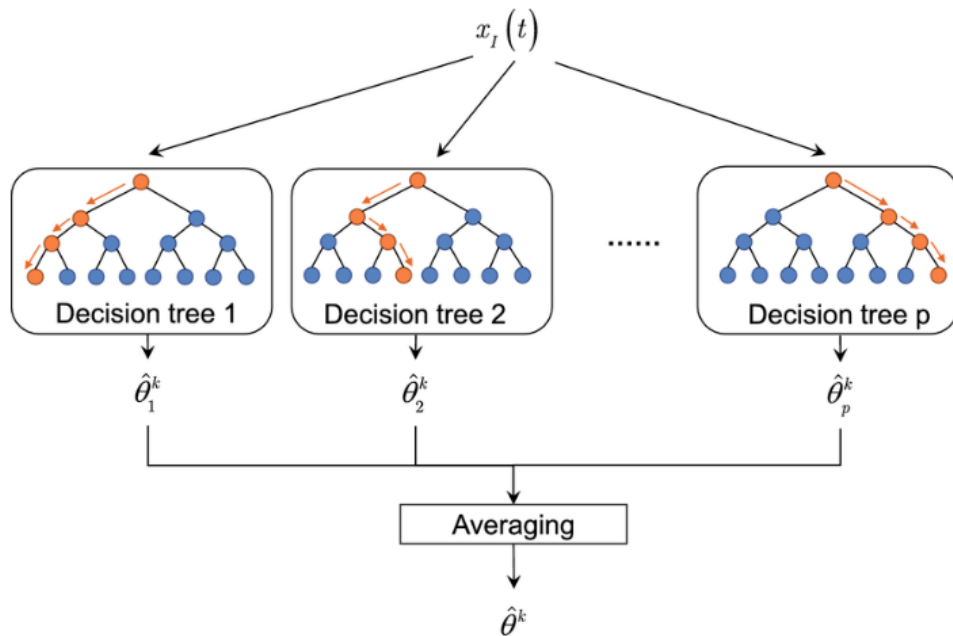
→ **Reduced subset of features:**
Instances of each cluster-
representative timeseries

	Target variable					Predictors						
	t_0	$\bar{C}_{NO2,(t_0)}$	$\bar{C}_{i,(t_0)}$	$\bar{P}_{(t_0)}$	$\bar{T}_{(t_0)}$	$\bar{S}_{p,(t_0)}$	$\bar{C}_{NO2,(t_0-1)}$	$\bar{C}_{NO2,(t_0-2)}$...	$\bar{C}_{NO2,(t_0-N)}$...	$\bar{T}_{(t_0-N)}$
	2021-01-01 00:00:00											
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	...											
	202x-xx-xx xx:xx:xx											

Z-levels



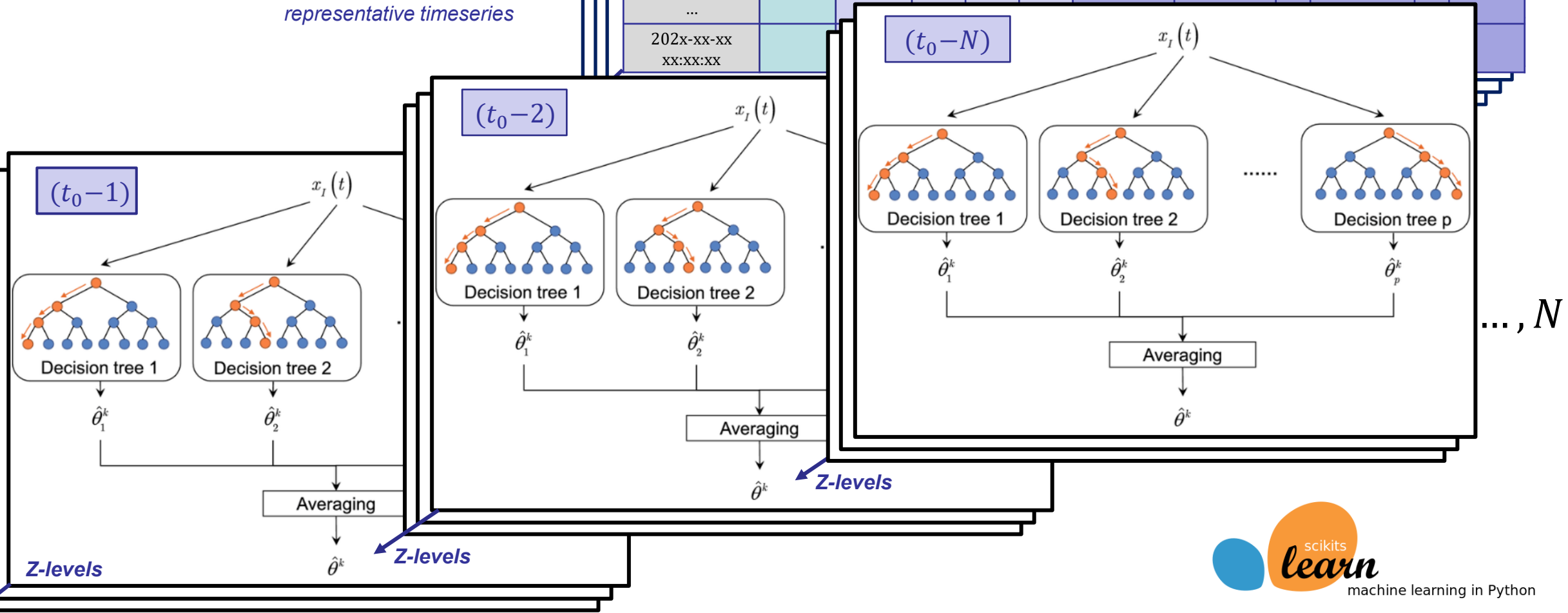
$$C_{NO2,(t_0)} \sim RF(\text{predictors}_{(t_0-k)}), \quad k = 0, 1, \dots, N$$



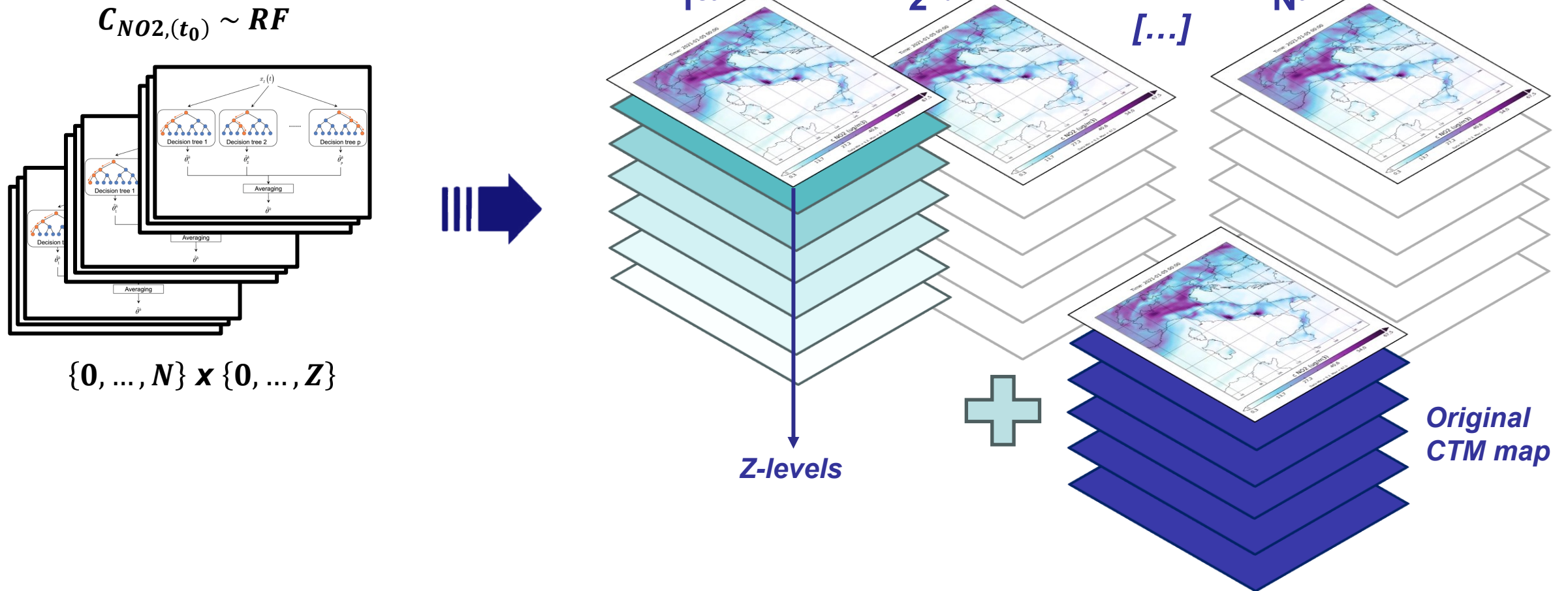
Step 3: Models Training

→ **Reduced subset of features:**
Instances of each cluster-
representative timeseries

	Target variable					Predictors					
t_0	$\bar{C}_{NO2,(t_0)}$	$\bar{C}_{i,(t_0)}$	$\bar{P}_{(t_0)}$	$\bar{T}_{(t_0)}$	$\bar{S}_{p(t_0)}$	$\bar{C}_{NO2,(t_0-1)}$	$\bar{C}_{NO2,(t_0-2)}$...	$\bar{C}_{NO2,(t_0-N)}$...	$\bar{T}_{(t_0-N)}$
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2021-01-01 01:00:00											
...											
202x-xx-xx xx:xx:xx											



Step 4: Prediction and 3D field assembly



Data Fusion experiment

- The ML-generated ensemble was tested in an offline Data Assimilation of S5p tropospheric NO₂ total columns observations in a FARM model simulations over the Italian domain during a two-month winter period.
- **Data Fusion/OI** as the analysis isn't used to update initial conditions for subsequent runs, viable under the hypothesis that **model uncertainties grow quickly** → **Stationary B**

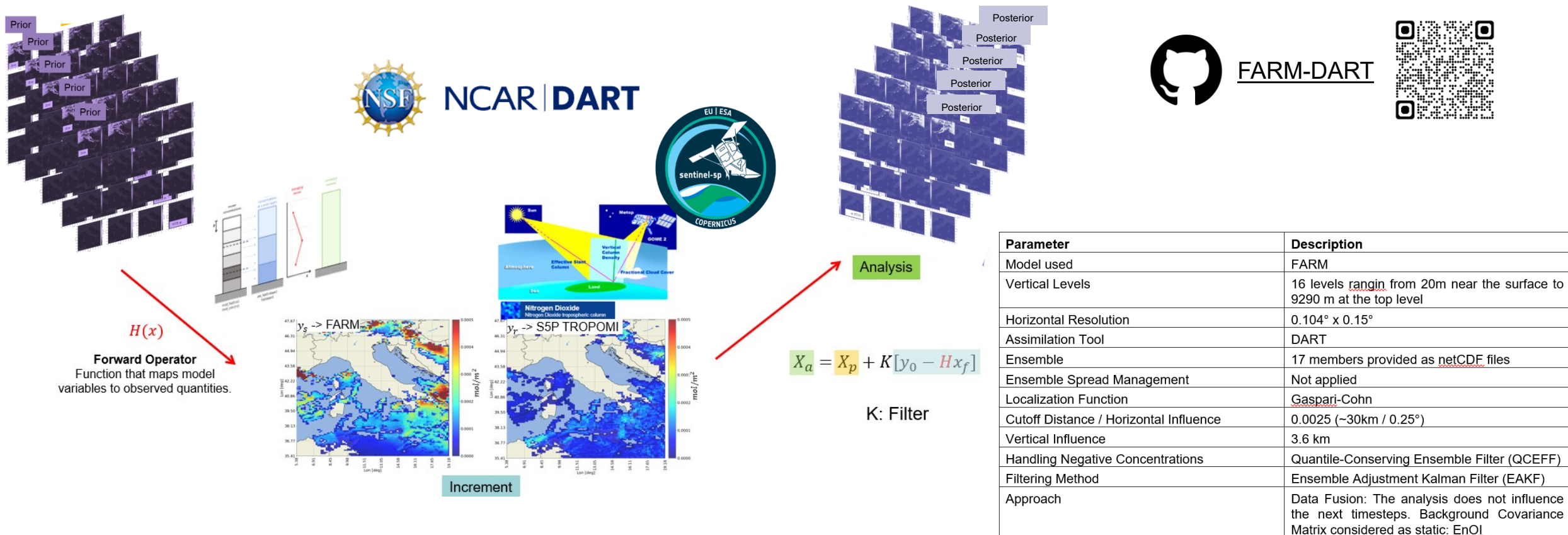
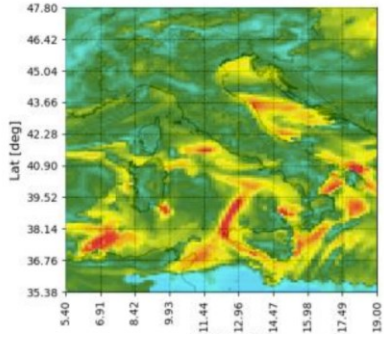


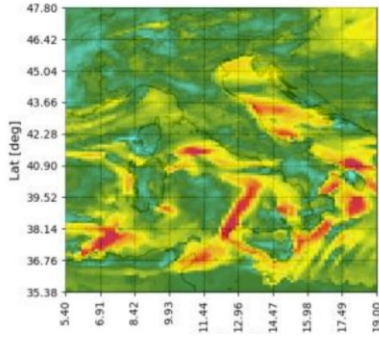
Figure 19. Summary Data Fusion experiment.

Ensemble insight – z-scores

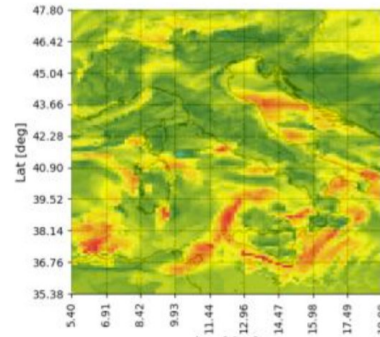
Member 1



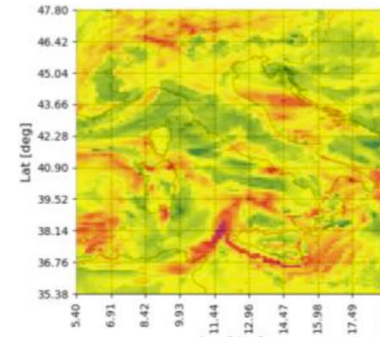
Member 2



Member 3



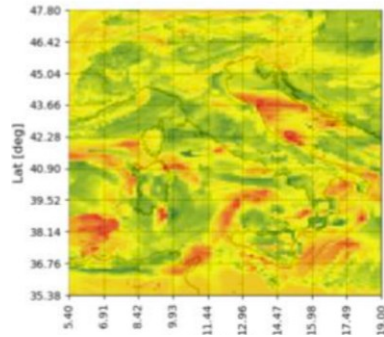
Member 4



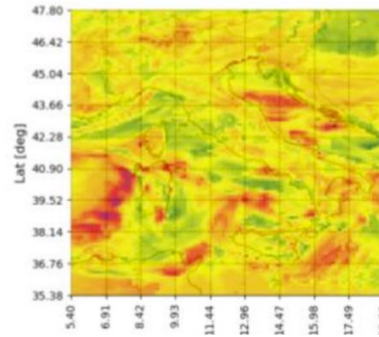
$$z = \frac{x - \mu}{\sigma}$$



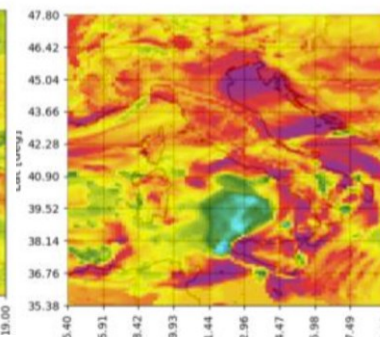
Member 5



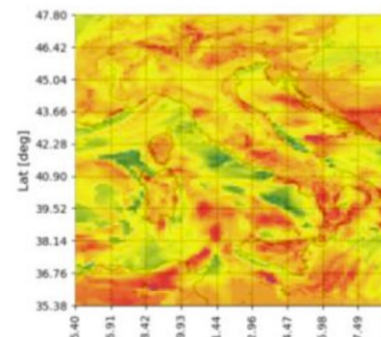
Member 6



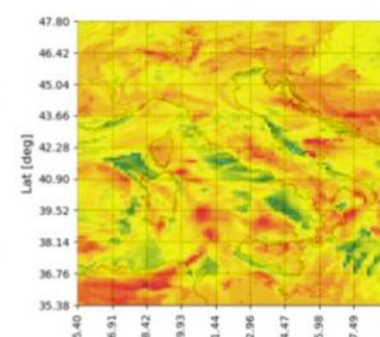
Member 7



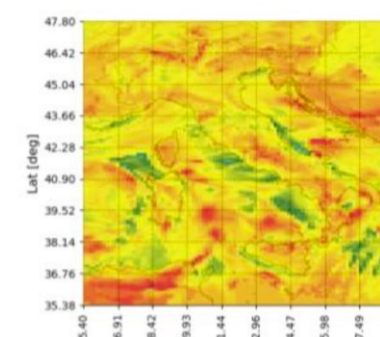
Member 8



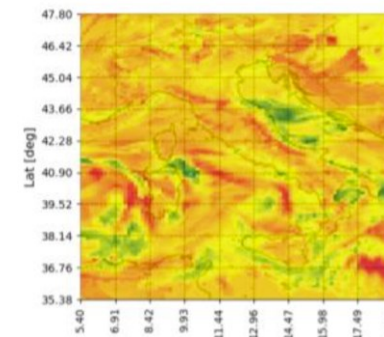
Member 9



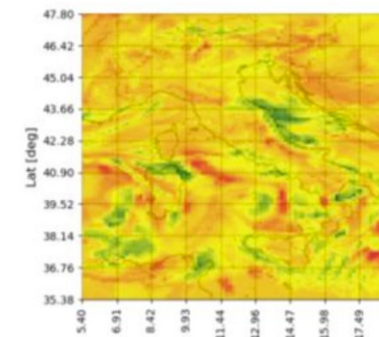
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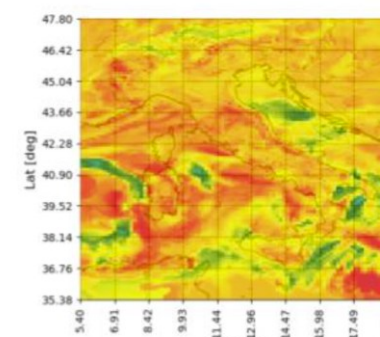
Member 11



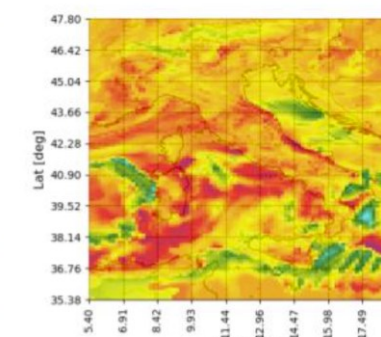
Member 12



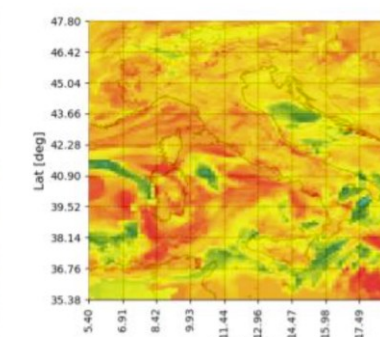
Member 13



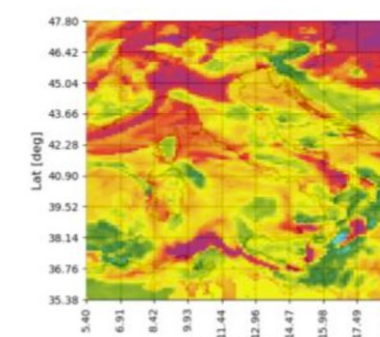
Member 14



Member 15

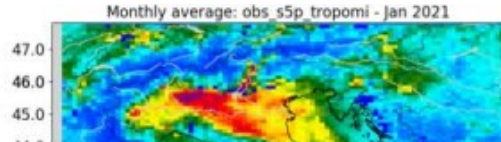


Member 16

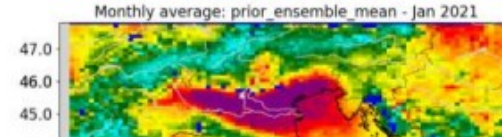


Data Fusion Results – 1

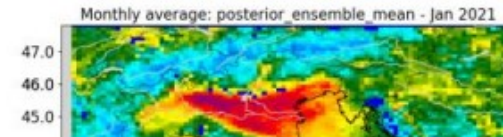
S5p NO2 vcd observations



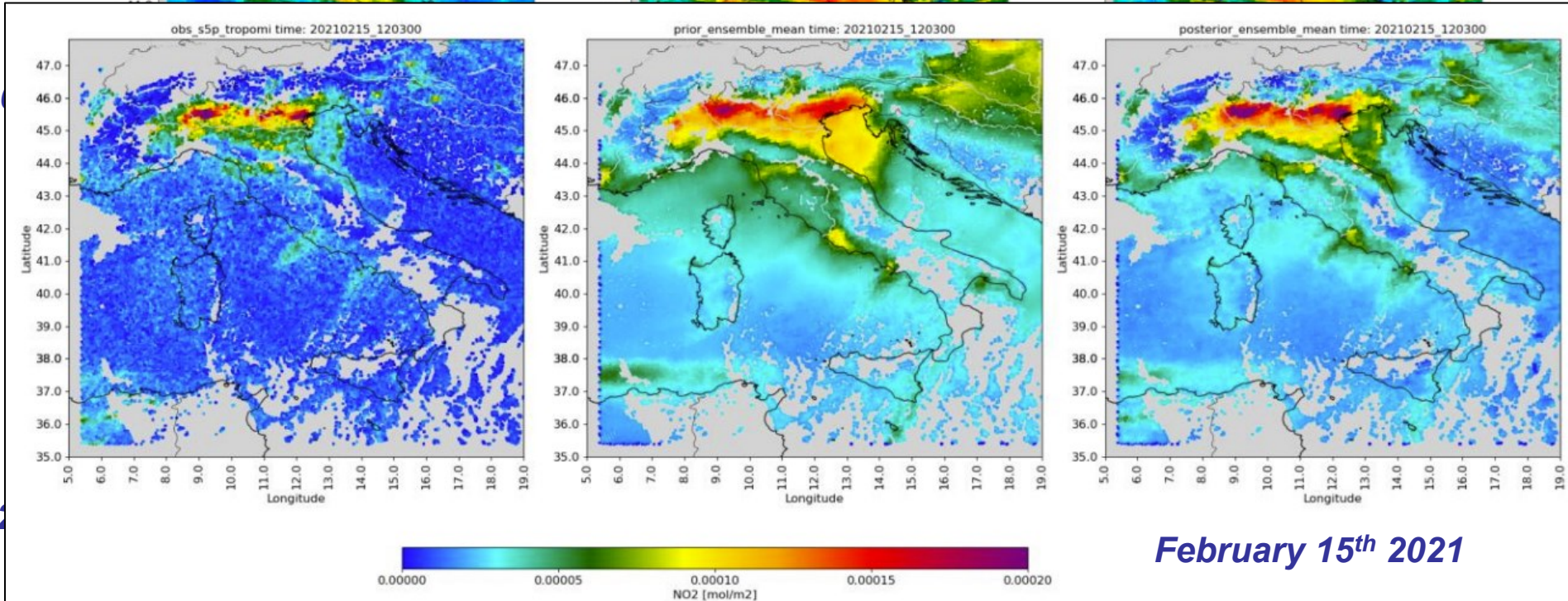
Prior NO2 vcd ensemble mean



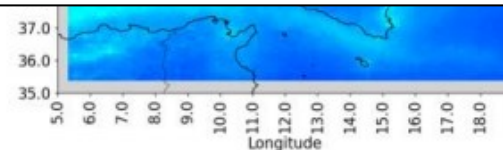
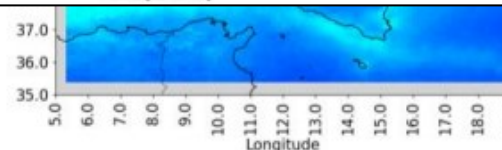
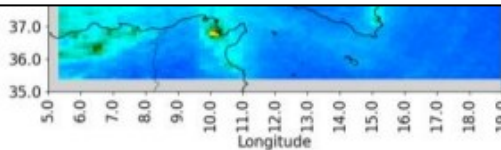
Posterior NO2 vcd ensemble mean



January 2021



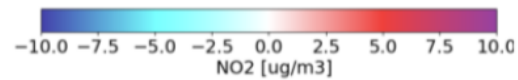
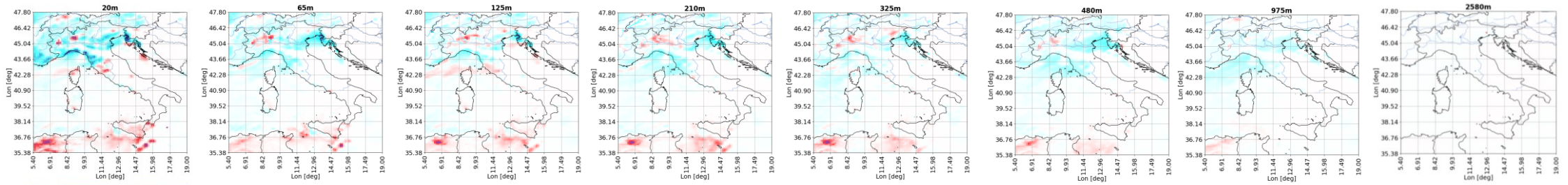
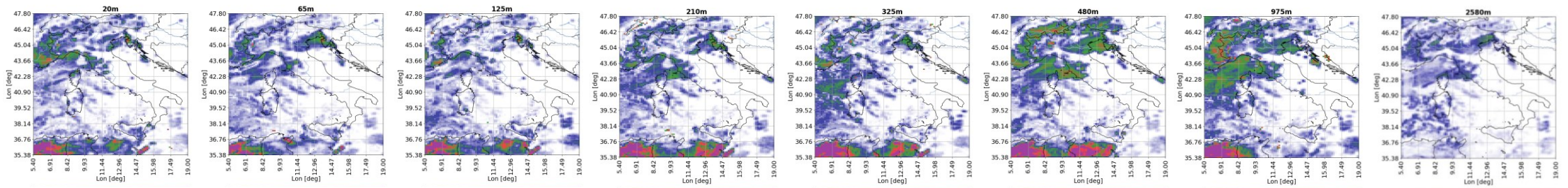
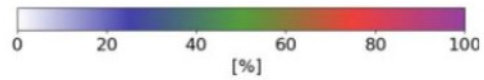
February 2021



Monthly means

Data Fusion Results – 2

$(\text{prior} - \text{posterior}) / \text{prior}$



$\text{prior} - \text{posterior}$

- ❑ A **computationally efficient** alternative to conventional **ensemble generation** methods has been presented
- ❑ Leveraging on **multiple RF regressors**, an ensemble of CTM runs was synthesized; a statistical representation of the **uncertainties in the model's forecast** can be drawn
- ❑ Preliminary results show the presented methodology can capture **both diagonal and off-diagonal covariance matrix terms**
- ❑ By avoiding the computational burden of starting N perturbed runs, **operational DA** of satellite data for air quality applications can be feasible for national level's PAs → *towards geostationary Sentinel-4*
- ❑ Further work will focus on enabling **online DA**, as well as on anchoring the ensemble mean to the original CTM run



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